L Number	Hits	Search Text	DB	Time stamp
-	4	JP-07270137-$.did. JP-07319525-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/12/17 11:13
-	2	JP-2000288968-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/12/17 11:34
-	74	((382/153).CCLS.) and (inspect$3 or measur$3 or measurement)	USPAT; US-PGPUB	2002/12/17 12:13
-	96	(382/153).CCLS.	USPAT; US-PGPUB	2002/12/17 11:53
-	70	((382/153).CCLS.) and (learn$3 or teach$3 or model or register$3 or registration)	USPAT; US-PGPUB	2002/12/17 12:30
-	233	robots! with (recogni$6 or regist$5)	USPAT; US-PGPUB	2002/12/23 08:24
-	44	B25J009/16.ipc.	USPAT; US-PGPUB	2002/12/17 14:26
-	24	B25J009/22.ipc.	USPAT; US-PGPUB	2002/12/17 14:27
-	476	G05B019/42.ipc.	USPAT; US-PGPUB	2002/12/17 15:22
-	22	watanabe-atsushi.in. and tokyo.inci.	USPAT; US-PGPUB	2002/12/17 15:17
-	7	arimatsu-taro.in.	USPAT; US-PGPUB	2002/12/17 15:19
-	159	G05B019/42.ipc. and (camera or photo$5 or picture or image or visual)	USPAT; US-PGPUB	2002/12/17 15:31
-	161	(382/152).CCLS.	USPAT; US-PGPUB	2002/12/17 15:35
-	310	(382/151).CCLS.	USPAT; US-PGPUB	2002/12/17 15:35
-	31	((382/152).CCLS.) and robot	USPAT; US-PGPUB	2002/12/17 15:35
-	43	((382/151).CCLS.) and robot	USPAT; US-PGPUB	2002/12/17 15:44
-	11	((plural$3 or multiple or dual or two or several or many) adj robot) same (video or camera or CCD or image or visual) same (workpiece or work-piece or (work adj part or piece) or model)	USPAT; US-PGPUB	2002/12/18 08:50
-	96	((plural$3 or multiple or dual or two or several or many) adj robot) and (video or camera or CCD or image or visual) same (workpiece or work-piece or (work adj part or piece) or model)	USPAT; US-PGPUB	2002/12/18 09:00
-	15	ax$s with (rotat$3 or turn$3) with (work-piece or work adj piece) same (register$3 or registrat$3 or teach$3 or learn$3)	USPAT; US-PGPUB	2002/12/18 16:05
-	119	ax$s with (rotat$3 or turn$3) with (workpiece or work-piece or work adj piece) same (register$3 or registrat$3 or teach$3 or learn$3)	USPAT; US-PGPUB	2002/12/18 10:34
-	37	(optical or camera) adj ax$s with (rotat$3 or turn$3) with (perpendicular or orthogonal) same (registering or registered or registrat$3 or teach$3 or learn$3 or inspect$3)	USPAT; US-PGPUB	2002/12/18 16:08
-	4	(optical or camera) near ax$s with (rotat$3 or turn$3) near ax$s with (perpendicular or orthogonal) same (registering or registered or registrat$3 or teach$3 or learn$3 or inspect$3)	USPAT; US-PGPUB	2002/12/18 16:06

-	5	(optical or camera) near ax$s with (rotat$3 or turn$3) near ax$s with (perpendicular or orthogonal) same (workpiece or work-piece or work adj piece)	USPAT; US-PGPUB	2002/12/18 12:48
-	2273	(382/141-154).CCLS.	USPAT; US-PGPUB	2002/12/18 13:12
-	656	ax$s with (rotat$3 or turn$3) with (perpendicular or orthogonal) same (registering or registered or registrat$3 or teach$3 or learn$3 or inspect$3)	USPAT; US-PGPUB	2002/12/18 13:14
-	7	((382/141-154).CCLS.) and (ax$s with (rotat$3 or turn$3) with (perpendicular or orthogonal) same (registering or registered or registrat$3 or teach$3 or learn$3 or inspect$3))	USPAT; US-PGPUB	2002/12/18 13:23
-	2	((382/141-154).CCLS.) and (robot same (ax$s with (rotat$3 or optical) with (perpendicular or orthogonal)))	USPAT; US-PGPUB	2002/12/18 13:23
-	11	robot same (camera or visual or CCD or optical) same (ax$s with rotat$3 with (perpendicular or orthogonal))	USPAT; US-PGPUB	2002/12/18 13:27
-	1	JP-04075887-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2002/12/18 14:01
-	0	6114824.URPN.	USPAT	2002/12/18 14:04
-	59	(robot with ax$s) same (train$3)	USPAT; US-PGPUB	2002/12/18 16:05
-	4	ax$s with (rotat$3 or turn$3) with (work-piece or work adj piece) same (train$3)	USPAT; US-PGPUB	2002/12/18 16:05
-	4	(optical or camera) near ax$s with (rotat$3 or turn$3) near ax$s with (perpendicular or orthogonal) same (train$3)	USPAT; US-PGPUB	2002/12/18 16:06
-	14	(optical or camera) adj ax$s with (rotat$3 or turn$3) with (perpendicular or orthogonal) same (train$3)	USPAT; US-PGPUB	2002/12/18 16:11
-	559	(382/154).CCLS.	USPAT; US-PGPUB	2002/12/18 16:11
-	87	((382/154).CCLS.) and (recogni$6 or identif$3 or identification) and robot	USPAT; US-PGPUB	2002/12/18 16:27
-	7	((382/154).CCLS.) and (reference or register$3 or registration or teach$3 or train$3 or learn$3) with (object or model or part or workpiece or work-piece or work adj piece) same robot	USPAT; US-PGPUB	2002/12/18 16:34
-	75	((382/154).CCLS.) and (reference or register$3 or registration or teach$3 or train$3 or learn$3) with (object or model or part or workpiece or work-piece or work adj piece) and robot	USPAT; US-PGPUB	2002/12/18 16:34
-	209	(robot with (camera or CCD or image or visual)) same (robot with (workpiece or work-piece or (work adj part or piece) or model))	USPAT; US-PGPUB	2002/12/18 08:28